

NAG Toolbox for MATLAB

f08nf

1 Purpose

f08nf generates the real orthogonal matrix Q which was determined by f08ne when reducing a real general matrix A to Hessenberg form.

2 Syntax

```
[a, info] = f08nf(ilo, ihi, a, tau, 'n', n)
```

3 Description

f08nf is intended to be used following a call to f08ne, which reduces a real general matrix A to upper Hessenberg form H by an orthogonal similarity transformation: $A = QHQ^T$. f08ne represents the matrix Q as a product of $i_{hi} - i_{lo}$ elementary reflectors. Here i_{lo} and i_{hi} are values determined by f08nh when balancing the matrix; if the matrix has not been balanced, $i_{lo} = 1$ and $i_{hi} = n$.

This function may be used to generate Q explicitly as a square matrix. Q has the structure:

$$Q = \begin{pmatrix} I & 0 & 0 \\ 0 & Q_{22} & 0 \\ 0 & 0 & I \end{pmatrix}$$

where Q_{22} occupies rows and columns i_{lo} to i_{hi} .

4 References

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

- 1: **ilo** – int32 scalar
- 2: **ihi** – int32 scalar

These **must** be the same parameters **ilo** and **ihi**, respectively, as supplied to f08ne.

Constraints:

if $n > 0$, $1 \leq ilo \leq ihi \leq n$;
if $n = 0$, $ilo = 1$ and $ihi = 0$.

- 3: **a(lda,*)** – double array

The first dimension of the array **a** must be at least $\max(1, n)$

The second dimension of the array must be at least $\max(1, n)$

Details of the vectors which define the elementary reflectors, as returned by f08ne.

- 4: **tau(*)** – double array

Note: the dimension of the array **tau** must be at least $\max(1, n - 1)$.

Further details of the elementary reflectors, as returned by f08ne.

5.2 Optional Input Parameters

1: **n** – int32 scalar

Default: The second dimension of the array **a**.

n , the order of the matrix Q .

Constraint: $n \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

lda, work, lwork

5.4 Output Parameters

1: **a(lda,*)** – double array

The first dimension of the array **a** must be at least $\max(1, n)$

The second dimension of the array must be at least $\max(1, n)$

The n by n orthogonal matrix Q .

2: **info** – int32 scalar

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

info = $-i$

If **info** = $-i$, parameter i had an illegal value on entry. The parameters are numbered as follows:

1: **n**, 2: **ilo**, 3: **ihi**, 4: **a**, 5: **lda**, 6: **tau**, 7: **work**, 8: **lwork**, 9: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

7 Accuracy

The computed matrix Q differs from an exactly orthogonal matrix by a matrix E such that

$$\|E\|_2 = O(\epsilon),$$

where ϵ is the *machine precision*.

8 Further Comments

The total number of floating-point operations is approximately $\frac{4}{3}q^3$, where $q = i_{hi} - i_{lo}$.

The complex analogue of this function is f08nt.

9 Example

```
ilo = int32(1);
ihi = int32(4);
a = [0.35, -0.1159524296205035, -0.3886010343233214, -0.2941840753473021;
     -0.5140038910358558, 0.1224867524602574, 0.1003597896821503,
     0.1125618799705319;
```

```

        -0.7284721282927631,  0.6442636185270625, -0.1357001717571131, -
0.09768162270493326;
        0.4139046183481608, -0.1665445794905699,  0.4262443722078449,
0.1632134192968561];
tau = [1.175095950769217;
       1.946022972139863;
       0];
[aOut, info] = f08nf(ilo, ihi, a, tau)

aOut =
    1.0000         0         0         0
         0   -0.1751   -0.9675   -0.1827
         0    0.8560   -0.2413    0.4572
         0   -0.4864   -0.0763    0.8704

info =
     0

```
